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GENERATION AND CONTROL OF POWER IN ISLANDED MICRO GRID USING RENEWABLE ENERGY SOURCES

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ABSTRACT

This paper presents a brand new strategy to regulate the generated power from energy sources existing in autonomous and isolated Micro grids (MG). During this specific study, the power system consists of a power convertor supplied by a energy storage system (ESS), that is employed to form the ac grid GFC (grid former converter), associate energy source supported a wind turbine, photovoltaic (PV) generation with its respective Power electronic converter GSC (grid supplier converter), and therefore the power consumers . The main objective of this proposed strategy is to regulate the state of charge of the battery bank ESS, wind turbine (WT), photovoltaic (PV) generation and loads, a coordinated active power regulation is needed to ensure efficient utilization of renewable energy, whereas keeping the ESS from overcharge and over discharge conditions .By limiting the voltage on its terminals by controlling the power generated by the energy sources.

This is often done without using dump loads or any physical communication among the power electronic converters or the individual energy source controllers. The electrical frequency of the micro grid is employed to inform the power sources and their respective converters regarding the quantity of indicate the practicability of the propose control strategy

Keywords- Battery banks, power control, renewable energy sources (RES's), isolated micro grids power that they need to generate in order to maintain the battery-bank charging voltage below or equal its maximum allowable limit

I. INTRODUCTION

Around the world, A major number of villages have no access to electricity because of their remoteness. Fortunately, in many of those places, like in oceanic islands; there are renewable energy sources , significantly solar radiation and wind energies also. These energy resources may be used to form isolated MG's to fulfill local energy needs [1], [2].

With the objective to electrify remote areas and energy islands, the micro grid conception is gaining more and more popularity. The MG is recommended by the Consortium or electric reliability Technology Solutions (CERTS) first. The consortium for electric reliability Technology Solutions (CERTS) initiated the analysis on the impact of connecting large amounts of distributed energy resources (DER) to low voltage networks so as to reinforce the reliability of the electric power system and developed the MG conception [1]. Resources like fuel cells, solar PV arrays and wind turbines along with power electronic converters, energy storage devices (i.e. batteries, super capacitors and flywheels) and customer loads, that could be operate independently. MG are often considered as a local grid with multiple distributed generators (DGs), ESS, and loads, ready to operate either in grid connected or islanded mode Micro grids will provide clean, reliable and uninterruptible power. Hence, the coordinated active power management strategy should take under consideration status of all micro grid components such as the State of Charge (SoC) of ESS, power offered from the Wind, PV systems by using battery banks, and demand of power consumption. Micro grids need outlined boundary, Industrial customer, campus, substation, match load and generation, voltage, frequency and power factor within tolerances. The applications of MG's will vary in storage, advanced controls, size in Mega Watts, generation resource sorts, micro-grid worth proposition. The MG's offers Energy security, grid independence capability and ensure energy supply for essential loads utilizing on site generation. MG's are amongst the major forthcoming entities which not only enable us to achieve this however additionally offer secured high quality power to the loads.

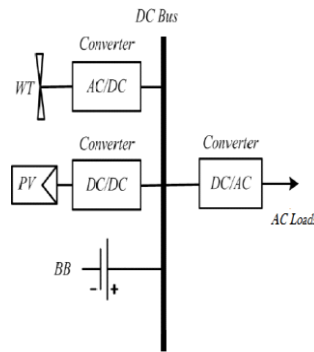


Fig.1. Proposed model for the Microgrid

MG has two typical operational modes:

Grid-connected mode and islanded mode [6]. Below traditional circumstances, the MG operates in grid-connected mode that is connected to the upstream grid, being either partly equipped from it or injecting some quantity of power into it. However, under emergency circumstances, the MG switches to islanded mode when a fault or link failure happens within the upstream grid, which disconnects from the upstream grid and operates autonomously promptly.

Grid Connected mode of operation:

The power Stream MG is connected to the distribution system and is supply energy to the grid using renewable solar or wind power. Keep electricity from the sodium Nickel Chloride, lithium ion Battery and Lead Acid Battery Systems also can be used to provide energy to the grid. Throughout the supply to Grid in operation mode, the gas generator won't be operated.

Island mode of operation:

During this mode renewable solar and wind generators are going to be primary source of power. Electricity stored within the Lead Acid, sodium Nickel Chloride and lithium ion Battery Systems may also be used at this point. Since all generation sources are intermittent with this operating mode, low priority MG loads may be disconnected reckoning on the amount of generation out there as shown in Fig.1 Here that we are considering that islanded mode of MG operation. There are many forms of topologies which are used to assemble isolated MG's. One chance is to connect all of the energy sources, as well as the battery bank, to a common AC bus, as exemplified within the system of Fig.2 in this figure WT stands for wind turbine, PV panel, and BB (battery bank). The DC voltage is converted to AC voltage to form the local power distributed network. Here, one bidirectional power electronic converter may be used to form the local power distribution network. An example of an isolated MG helpful for applications with distributed energy sources is shown in Fig.3 in this figure, GFC stands for grid former converter, GSC stands for grid supplier converter that's fed by a primary energy supply, and $Z_{i,j}$ is that the line impedance between the i bus and therefore the j bus.

A crucial issue associated with these autonomous and distributed MG's is to regulate the power generated internally to maintain the system energy balance so as to keep the terminal voltage of the BB restricted to a secure value and consequently maintain its SoC under control. Another chance is to use physical communication (wiring) between the converters to inform their control systems regarding the balance of energy in the MG and therefore the amount of power that each of them should generate to keep this energy balance under control. It consider that each one the power converters operate as a voltage source and follow the conventional droop control strategy, as represented in [7]. Once the SoC of the battery bank tends to its maximum value, the reference frequency of the system, previously determined based on the droop control strategy, is incremented by a particular value. This increase in frequency implies a reduction in power generated by the other sources, resulting in a reduction within the power absorbed by the battery bank.

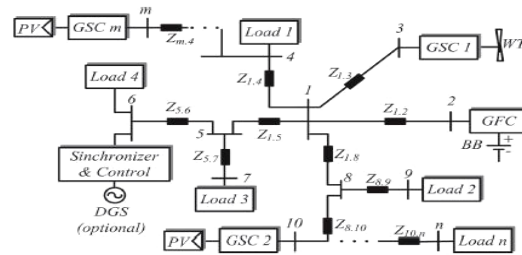


Fig.2. Micro-grid example with DC and AC bus

This paper proposes strategy to regulate the generated power within an isolated ac MG with distributed RES. The proposal is to regulate the terminal voltage of the existing BB below or equal its maximum allowable value. This is often done by limiting the amount of power that every energy source will generate at every instant, as shown in [3]. The MG frequency is employed to characterize the state of charge of the BB and quantify to the converters' control systems what proportion power they have or will generate to maintain under control the internal power balance of the MG.

The control of the BB terminal voltage implies indirectly the management of their SoC. The main contributions of this description of the converter controllers and a brand new methodology to control the generated power by the wind turbine, and PV cell by a brand new design and standardization of the terminal voltage controller of the BB, and by the presentation of experimental results, as well as variable wind speed operation and constant wind speed. This micro-grid is employed to show the feasibility of the proposed strategy.

II. SYSTEM DESCRIPTION

Fig.3 illustrates the simplified diagram of a islanded micro-grid used to justify the control strategy projected during this paper. It consists of a GFC, a GSC, PV cell and a BB. The renewable energy source, during this specific study, could be a variable speed wind turbine coupled to a permanent-magnet synchronous generator (PMSG). Reckoning on the system size, other energy sources and alternative storage energy systems is distributed along the MG.

The system is useful to show the feasibility of the proposed control strategy without losing generality. The GFC may be a bidirectional converter shaped by a pulse width modulation (PWM) three-phase {inverter electrical converter} and a dc–dc converter that works during a buck mode when the BB is under charge or in a very boost mode when it's under discharge. The PWM inverter controls the magnitude and frequency of the micro-grid voltage, while the dc–dc buck or boost converter is used to control the voltage at the dc bus capacitor (C_{dc}) which is the dc bus voltage as well as the charging and discharging of the BB. The GSC is employed to control the power generated by the renewable energy source. During this explicit example, the converter is formed by a conventional back-to-back topology [12]. It has a grid-side PWM inverter (GSI) and a wind turbine-side PWM inverter (TSI). The GSI is employed to control the dc-link voltage of the back-to-back topology, and also the TSI is employed to control the power generated by the wind turbine supported a maximum power point tracker (MPPT) formula. The grid voltage controller uses the standard configuration enforced on a synchronous dq reference frame, with an inner current loop and an outer voltage loop [7].

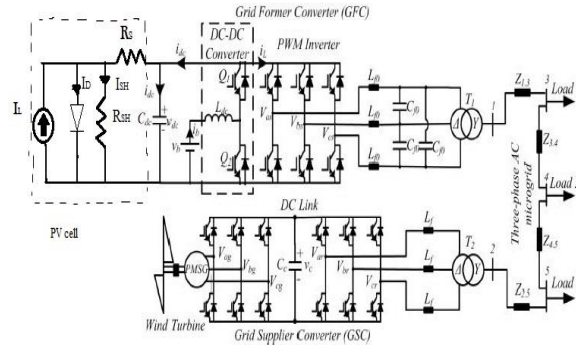


Fig.3.Simplified diagram of the studied micro-grid

The frequency and voltage reference values are calculated using droop control strategy as functions of the active and reactive power respectively at the GFC terminals.

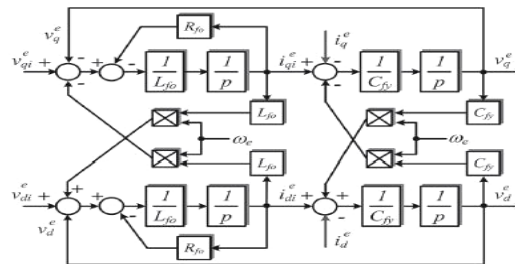


Fig.4. Block diagram of LC filter implemented in a synchronous reference frame

III. GRID FORMER CONVERTER

A. Control of the Micro grid Voltage and Frequency:

The MG voltage controller uses the standard configuration enforced on a synchronous dq reference frame, with an inner current loop and an outer voltage loop. The frequency and voltage reference values are calculated using droop control strategy as functions of the active and reactive power severally at the grid former converter terminals. The dq model of the LC filter in the delta side of transformer T1(see Fig.3) is employed to design the control loops of the GFC. Where R_{f0} is the equivalent series resistance of the filter inductor L_{f0} ; ω_e is the MG frequency in radians per second, the superscript “e” denotes variables within the dq synchronous reference frame, i_{ed} and i_{eq} are the dq currents within the delta side of transformer T1; C_{fy} is that the per-phase equivalent capacitance of the LC filter and is up to $3Cf_0$; and are the dq voltages within the capacitors of the LC filter.

The subscript i denotes the output variables of the GFC PWM inverter. All the block diagrams shown during this paper use the operator $p = d/dt$. Based on the model presented in Fig.4, an inner current loop and an outer voltage loop were designed, as illustrated in Fig.5. In this figure, “ \wedge ” denotes calculable parameters, and GDID1 is the transfer function accustomed decouple at the sample instants the effect of the disturbances as a result of the load currents “ e ” and the cross-coupling due to v_q^e and v_d^e . ZOH means that zero-order hold (latch). Basically, this on the inductance is controlled so as to control the voltage on the capacitance independently whether the power flux is from the PWM inverter to the micro-grid or contrariwise (vice versa).

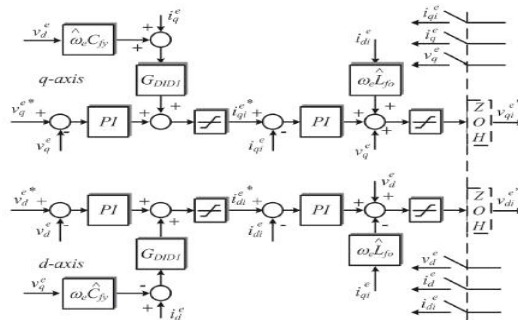


Fig.5. Block diagram of the Micro grid voltage controller.

The voltage reference values for the voltage controllers will be constant, typically adequate to the nominal value of the micro grid voltage, or will be calculated based on a droop control strategy. During this paper, the voltage reference was mounted in 220 V(*rms* line voltage within the delta side of T1). By considering that the *dq* synchronous reference frame is aligned with the micro grid voltage vector, the reference values of the *dq* voltages are $v_d^e = 0V$, and $v_q^e = 179.6V$. The frequency reference value is calculated by using the power control strategy.

B. Control of the Bidirectional DC–DC Converter

The dc–dc converter (in GFC) is employed to regulate the voltage in the capacitor C_{dc} . The action of the controller of the dc–dc converter will be considered comparable to connecting a controlled voltage source, with mean value V_{ct} , between the *xy*. Terminals of the converter circuit, as shown in Fig. 7(a) and (b). If the losses within the converter aren't considered, the voltage on C_{dc} depends solely on the difference between the power at the BB terminals (P_b) and (P_{inv}) that is the power at the terminals of the delta side of the isolation transformer T1, which is positive once the power flux is from the inverter to the grid and negative on the contrary. This is often shown in Fig. 7(c). Therefore, the dynamic equation for v_{dc} will be written as in (1), wherever ω_{dc} is an auxiliary variable defined by $\omega_{dc} = v_{dc}^2$

$$\frac{1}{2} C_{dc} \frac{d v_{dc}^2}{dt} = \frac{1}{2} C_{dc} \frac{d \omega_{dc}}{dt} = P_b - P_{inv} \quad (1)$$

IV. GRID SUPPLIER CONVERTER

A. Control of the Injected Current in the Micro grid and the Voltage at the DC Bus

In this paper, the GSI of the GSC (see Fig.3) is employed to control the dc bus voltage of the back-to-back topology. This controller uses an inner current loop to regulate the injected current within the micro grid. The current controller is enforced in a *dq* synchronous reference frame aligned with the micro grid positive sequence voltage vector. The converter variable synchronization is completed by employing a synchronous phase-locked loop (PLL) that has a second-order resonant filter tuned for the fundamental frequency of the micro grid. This PLL additionally contains a module to extract the instantaneous positive and negative symmetrical components of the voltage of the micro grid [13]. The PLL was tuned based on its tiny signal analysis model for a band width of 100 Hz.

The diagram of the current controller along with the filter (L_f) model during a synchronous reference frame is illustrated in Fig.6, wherever R_f is that the equivalent series resistance of the inductor, if i_{qs}^e and i_{ds}^e are the currents in the delta side of transformer T2, and e_{qs}^e and e_{ds}^e are the dq axis components of the micro-grid voltage. The adopted current direction references are an equivalent as those shown in Fig.3. If the losses within the GSI and within the inductor L_f are neglected, the variation of the energy stored within the capacitor C_c is equal to the difference between the active powers received from the MG (P_s) and therefore the active power generated by the wind turbine (P_g). Using the convention of Fig.3, this could be expressed as in

$$\frac{1}{2} C_c \frac{d \omega_c}{dt} = P_s - P_g; \omega_c = v_c^2. \quad (2)$$

For a dq synchronous reference frame aligned with the micro grid voltage vector, it follows that $e_{ds}^e = 0$. Therefore, P_s is adequate to $(3/2)E_s i_{qs}^e$, with E_s being the magnitude of the part voltage, thought-about constant in this application. By defining K_c adequate to $(3/2E_s)$, the dynamic equation for the capacitor C_c is presented in

$$\frac{d\omega_c}{dt} = \frac{2}{C_c} (K_c i_{qs}^e - P_g) \quad (3)$$

B. Control of the Wind Turbine Generated Power

The power generated control strategy uses the TSI to regulate the torque of the PMSG, leading to the control of its generated power. The torque control relies on the control of the generator current. The TSI current controller is implemented on a synchronous dq reference frame aligned with the rotor of the wind turbine generator. Based on the conventions adopted in this work, the d-axis current component (i_d) of the generator is controlled to be zero. Thus, in steady state, the generator torque (T_g) is proportional to its q-axis current reference component (i_q^*), as shown in (4) [14], wherever k_g is given by (5), P is the number of generator poles, and λ_{mf} is that the generator permanent-magnet flux

$$T_g = K_g i_q^* \quad (4)$$

$$K_g = \left(\frac{3}{2}\right) \left(\frac{P}{2}\right) \lambda_{mf} \quad (5)$$

The mechanical torques of a wind turbine as a function of the rotational speed of the wind turbine (ω_R) for different wind speeds. When the wind turbine works on its point of maximum power production, the mechanical torque (T_M) made is proportional to the square. Of ω_R , as indicated by T_{Motm} where K_{Totm} could be a constant that depends on the physical and operational characteristics of the turbine and on the air density. The value of K_{Totm} could also be obtained by experimentation or from computational simulations, based on mathematical models of the turbine [15].

$$T_M = T_{Motm} = K_{Totm} \omega_R^2 \quad (6)$$

One possible MPPT algorithmic rule for the turbine is often implemented by making the generator torque curve coincide with the optimum curve of the turbine mechanical torque ($T_g = T_{Motm}$) [16]. As a result, the reference value for the q-axis generator current (i_q^*) is given by

$$i_q^* = (K_{Totm} / K_g) \omega_R^2 = K_{iq} \omega_R^2 \quad (7)$$

V. PROPOSED STRATEGY TO CONTROL THE GENERATED POWER IN THE MICROGRID

In stand-alone and distributed renewable energy systems, there is no commercial or conventional grid to absorb any surplus power generated internally within the micro grid. Therefore, the generated power must be controlled when the load power is less than the quantity of power that might be generated by the energy sources. This can be necessary to keep the energy balance in the MG under control and to keep the BB voltage below or equal its maximum allowable value. This can be necessary since voltages more than the gasification voltage will decrease the life span of batteries or maybe harm them irreversibly [17].

In the proposed control strategy, the GFC verifies the BB voltage to understand if it reached the maximum allowed charging voltage and, if so, modification the MG frequency to inform the other sources that they need to reduce their generated power. Based on the MG frequency, the control systems of the power generation sources connected to the MG decide whether or not to limit the power generated by each of them.

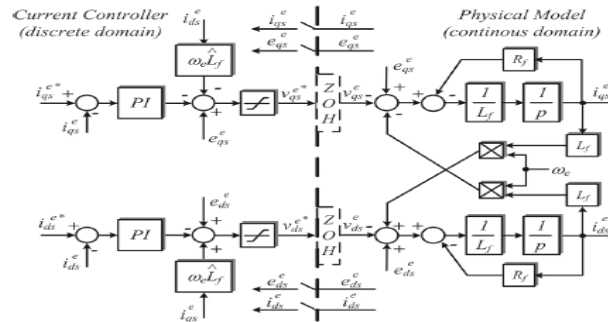


Fig.6. Block diagram of the control of the injected current in the micro-grid by the GSC.

This control strategy is explained based on Fig. 9. While the terminal voltage of the battery bank is below its maximum limit, the MG frequency (f) is set according to the conventional droop control strategy, represented by line C_1 in Fig.9, since a physical or virtual inductance is added once the line resistance can't be neglected [7]. The frequency value is calculated by (8), wherever k_p is that the slope constant of the line C_1 .

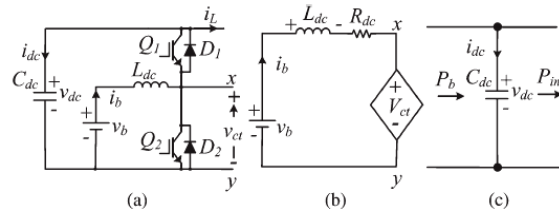


Fig.7. DC–DC converter average model: (a) Original circuit, (b) equivalent average circuit of inductor and battery bank, and (c) average model of the bus dc.

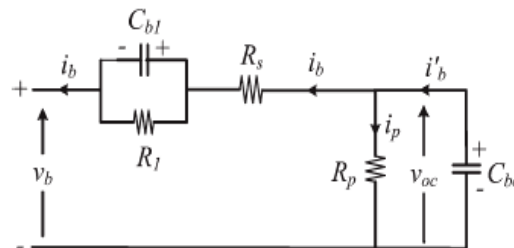


Fig.8. Lead–acid battery equivalent circuit

On this case, there aren't any restrictions concerning the amount of power that may be generated, and therefore the existing renewable energy sources will function on their maximum power point. Obviously, this is true as long as the battery bank has been designed with sufficient capability to absorb all the power that the renewable sources will produce at a given instant.

$$f = f_0 - k_p P_{inv} \tag{8}$$

On the other hand, if the maximum voltage of the battery bank is reached, the MG frequency is imposed to be always higher than the value f_{max} that is that the maximum frequency of operation of the conventional droop control strategy. This is illustrated by the hatched area in Fig.9. Now, the value of the frequency (f) could be a variable that changes dynamically with the terminal voltage of the battery bank (v_b), the power generated internally within the micro-grid (P_g), and therefore the power of the GFC (P_{inv}). This could be expressed by (9).

Because the calculation of the frequency depends on the dynamics of the v_b voltage controller, its relationship with the power (P_{inv}) will not follow a well-defined algebraic equation as, as an example, a straight line. Therefore, Fig.4

shows solely an illustration that the frequency can assume any value between f_{max} and $f_{max} + \Delta f_{max}$. During this operating condition, it's necessary to limit the amount of power which will be generated by renewable sources ;otherwise, the integrity of the battery bank is in danger. The amount of power that needs to be reduced from the maximum power that each source is ready to supply at every moment has a direct relation to the frequency difference $\Delta f = f - f_{max}$. The values of f_0 and $\pm \Delta f_{max}$ adopted during this work are 60 Hz and ± 0.60 Hz in order that the frequency range of the MG is between 59.4 Hz (f_{min}) and 61.2 Hz ($f_{max} + \Delta f_{max}$), which meets the European standard EM50160 [18].

$$f = f_{max} + \Delta f(v_b, P_g, P_{inv}) \tag{9}$$

A. Implementation of the Proposed Strategy in the GFC

The control of the battery bank voltage, so as to ensure its integrity, was implemented while the output of the hysteresis loop is zero, the value of the frequency reference is $f_e^* = f_1$. On the other hand, whereas the output of the hysteresis loop is one, a proportional and integral (PI) controller is used to regulate the terminal voltage of the battery bank equal or below its maximum allowed value (V_{bmax}). The output of this controller is that the increment of frequency (Δf) that has to be added to the value f_{max} to form the new micro-grid frequency reference value ($f_e^* = f_2 = f_{max} + \Delta f$). The value of Δf is proportional to the amount of power that has to be decremented from the generated power in order to control the battery bank terminal voltage. The low-pass filter with a 1-Hz bandwidth is employed to avoid sudden variations in frequency due the hysteresis loop.

B. Implementation of the Proposed Strategy in the GSC

The grid frequency is measured by the GSC and if its value is higher than f_{max} , it means the voltage of the battery bank is higher than its maximum allowed value. For the actual case where the renewable energy source could be a wind turbine, the GSC power controller decrements the current reference i_q^* , originally calculated by (7), that is currently calculated by (10), where K_f is a constant That serves to match the rated power of the GFC with the rated power of the wind turbine.

$$i_q^* = K_{iq} \left(1 - \frac{\Delta f}{\Delta f_{max}} \right) \tag{10}$$

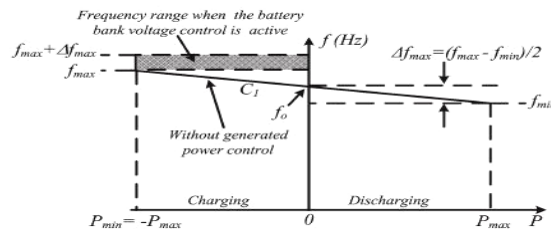


Fig.9. Frequency versus power in the GFC based on the proposed power control

C. Tuning of the Battery Bank Terminal Voltage Controller

The standardization of the PI controller shown in Fig. 12 takes into account the dynamic of the battery bank. One possible model for lead-acid batteries is shown in Fig.8 [19].

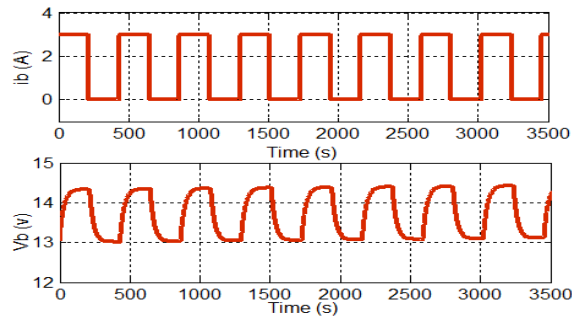


Fig.10. Simulation waveforms during the tests with a 30-Ah 12-V lead-acid battery. (a) Current. (b) Voltage.

In this Fig.7, v_{oc} is that the battery open circuit voltage, R_s is that the equivalent series internal resistance, R_1 and C_{b1} are used to model the over- or under voltage that happens once the battery is charging or discharging, R_p is that the resistance due the natural losses, and C_{b0} models the battery capacity to storage energy. Normally, the natural losses occur terribly slowly, therefore the effect of R_p will be disregarded for the aim of this work.

The voltage and current waveforms of a battery of 30 Ah and 12 V, obtained throughout testing to estimate the parameters of the equivalent circuit, are shown in Fig.10. The calculable parameters obtained after a charging cycle, once the voltage of the battery is approximately 14.3 V are $R_s = 8.7 \text{ m}\Omega$, $R_1 = 431.40 \text{ m}\Omega$, $C_{b1} = 64.93 \text{ F}$, and $C_b = 49,091.00 \text{ F}$. From the separameters, it will be seen that the smallest time constant related to the dynamics of the battery was 28.01 s ($R_{b1}C_{b1}$). The variation of the micro grid frequency (Δf), because the output of the battery voltage controller (PI), has a direct relationship with the amount of power ΔP that should be reduced of the overall power generated within the micro grid. A variation ΔP within the power at the battery bank terminals implies a variation of Δi_b within the current of the battery bank. This variation is approximately given by

$$\Delta i_b \cong \Delta P / V_{bmax} \tag{11}$$

Where, $G_{fp}(p) = \Delta P_p / \Delta f(p)$ and $G_b(p) = \Delta V_b(p) / \Delta i_b(p)$. From the equivalent circuit shown in Fig.6, it is deduced that the transfer function $G_b(p)$ is given by (12). Typically, $G_b(p)$ has much slower dynamics than $G_{fp}(p)$, therefore $G_{fp}(p)$ is approximated by

$$G_b(p) = (R_s + \frac{1}{R_1 C_{b1}} + \frac{1}{C_{b0}}) \tag{12}$$

$$G_{fp}(p) \cong 1/kp \tag{13}$$

The PI controller of was tuned based on the Battery bank parameters in order that the dynamic response of the closed-loop system had a time constant of roughly 20 times smaller than the time constant $R_{b1}C_{b1}$ of the battery model.

VI. SIMULATION RESULTS

A. Results with Constant Wind Speed

Fig.11 shows the action of the proposed control strategy over the battery bank voltage and also the MG frequency once the battery bank is fully charged and also the wind turbine is able to generate power. In this experiment, the wind speed was considered constant and adequate to 9.2 m/s. Before the tests, the battery bank was fully charged (before the time of 0 s in Fig.11), and its open circuit voltage is 258 V. At the instant of 0 s, the GFC is turned on, and also the MG is at no load, supplying just the system losses. Until t_1 , the MG remains at no load, and its frequency is kept constant [see Fig.11(c)] following (8). At instant t_1 , the GSC is turned on, starting to inject the wind turbine power (4.5 kilowatt at GFC terminals) into the MG. Because the system is at no load, this power goes to the battery bank [see battery current in Fig.11(d)]. Whose voltage will increase, reaching its maximum value (280 V) at time t_2 . At this instant, the power controller begins to act, keeping the battery bank voltage at 280 V. The controller keeps the frequency on top of

$f_{max} = 60.6$ Hz. As a result, the generated power is reduced [see Fig.11 (a)] to keep the BB voltage under control. At instant t_3 , a load of 7.05 kilowatt is connected to the micro grid

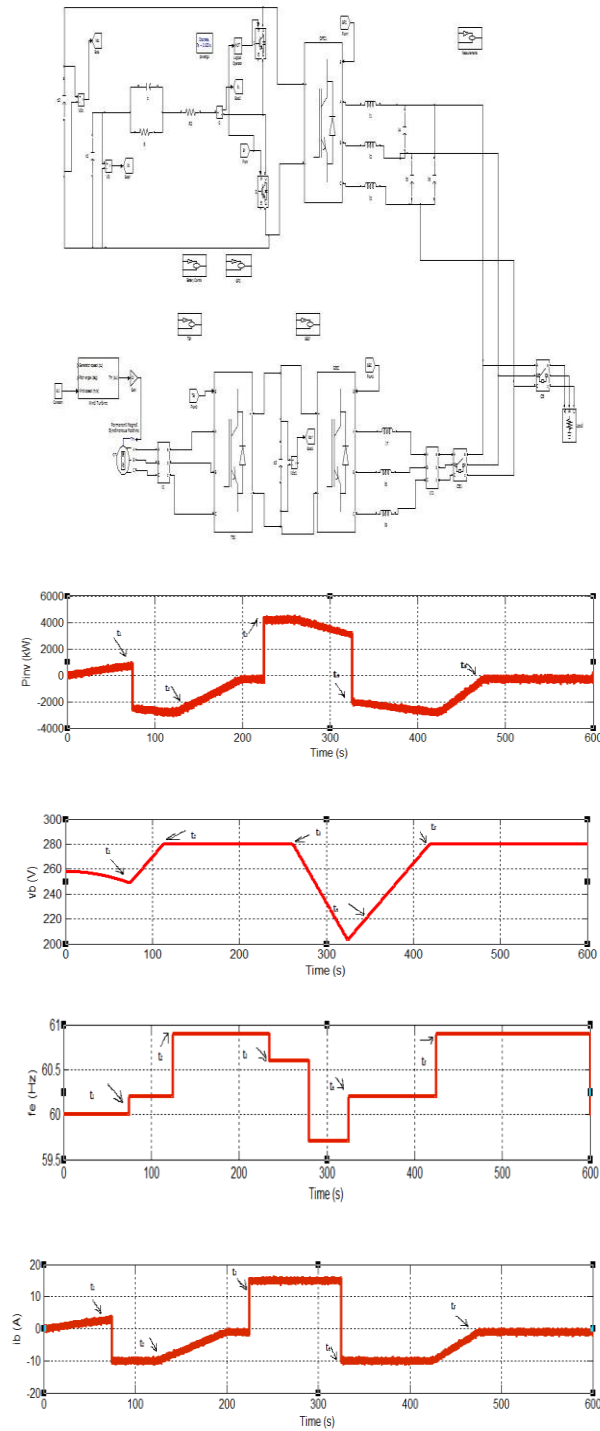


Fig.11. Operation with a constant wind speed of 9.2 m/s: (a) Power at the GFC terminals, (b) battery bank voltage, (c) Micro grid frequency, and (d) battery current.

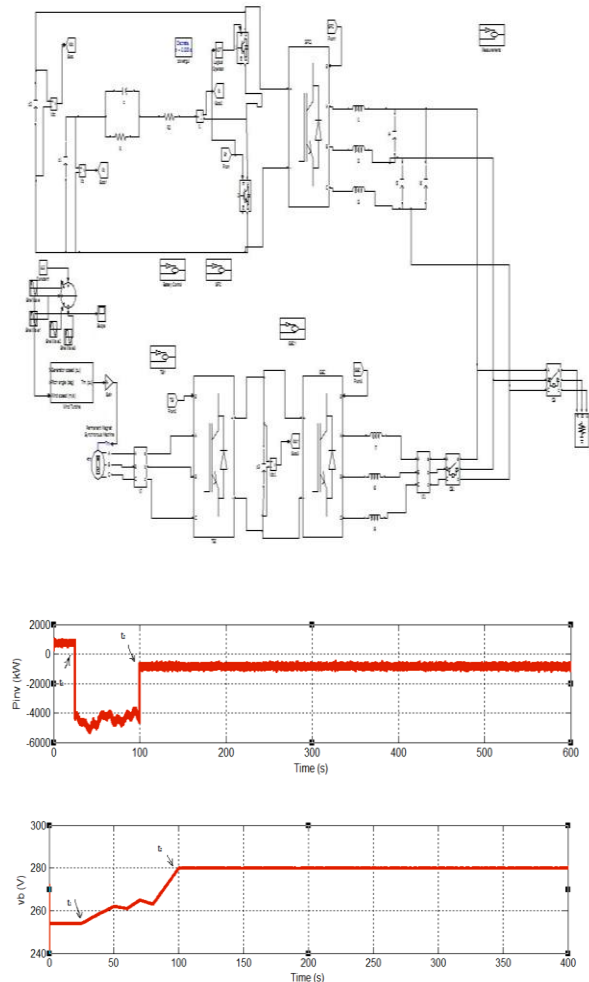
Because there's additional power demanded by the load than the generated power, the battery bank provides a part of the load, and its terminal voltage begins to decrease. At instant t4, the load was disconnected. The battery bank begins to recharge, and at instant t5, its voltage reaches once more 280 V. From this point, the proposed control strategy comes into operation ,regulating the terminal voltage at 280 V, though there's wind and also the wind turbine is in a position to generate power. Fromt5, the battery bank remains charging, however with constant voltage and charge current decreasing with its SOC. Lead–acid battery manufacturers suggest this charging characteristic.

B. Results with Variable Wind Speed

Fig. 12 shows the system behavior for variable wind speed. The wind speed was synthesized in the wind turbine emulator based on the model presented in [20]. In this model, the wind speed (V_W) is given by (14), with an average speed of 8.5 m/s, $\omega = 2\pi/t_W$, and $t_W = 120$ s

$$V_W = 8.5 + 0.6 \sin(\omega t) + 0.6 \sin(3.5 \omega t) + 0.3 \sin(12.35 \omega t) + 0.06 \sin(35 \omega t) \tag{14}$$

Fig. 12, the micro grid is functioning with no load, supplying only the system losses, and therefore the GSC is turned off before the instant t1. At instant t1, the GSC is turned on, and power flows to the battery bank, as shown in Fig. 12(a) and (d). Its voltage begins to increase until it reaches 280 V at instant t2 [see Fig. 12(b)]. At this instant, the power controller begins to act, reducing the generated power in order to keep the battery bank voltage under control with mean value approximately equal to 280 V.



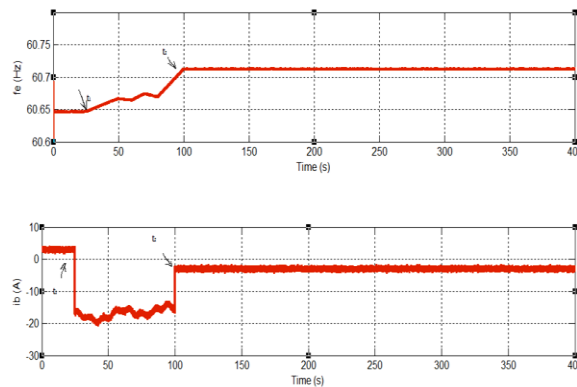
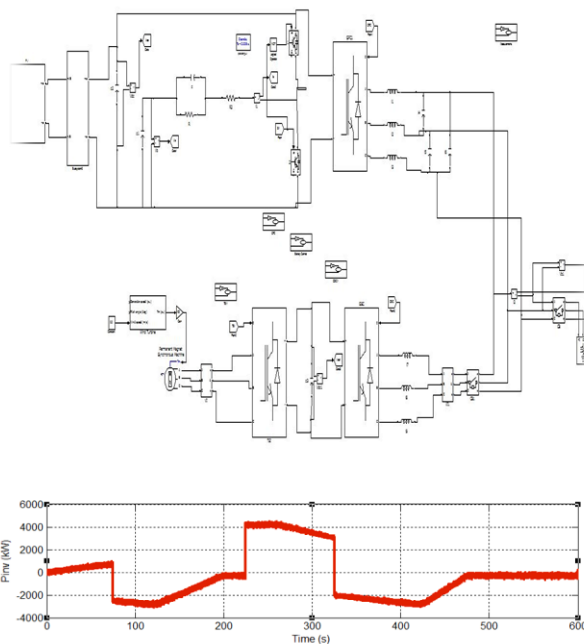


Fig. 12. Operation with variable wind speed: (a) Power at the GFC terminals, (b) battery bank voltage, (c) microgrid frequency, and (d) battery current.

C. Results with constant speed when a PV cell connected to the MG

while a lot of complete description of autonomous active power control in full range of SoC, and its implementation taking into consideration the ESS and PV system prime sources are self- addressed.

Battery bank system is employed because the ESS which fixes bus frequency and compensates power imbalance between power generation and consumption. Every PV system is employed to supply renewable energy to the micro-grid. Fig.13 shows the system at constant wind speed with the connection of PV cell with constant wind speed as 8.5 m/s, snubber resistance $R_s = 500 \Omega$, snubber capacitance $C_s = 25 * e^{-10} \text{ F}$, and as the forward voltage as 100V, and resistance in parallel to the diode is 10K Ω , by simulating this model that we achieved these results.



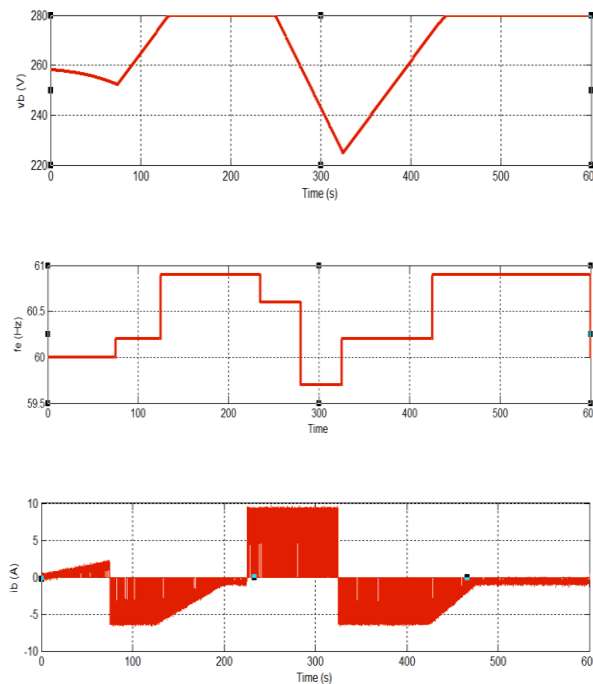


Fig. 13. Operation with a constant wind speed of 9.2 m/s & PV cell: (a) Power at the GFC terminals, (b) battery bank voltage, (c) microgrid frequency, and (d) battery current.

VII. CONCLUSION

This paper conferred a technique to regulate the generated power in order to keep the charging voltage battery banks under control in islanded micro grids with distributed renewable energy sources. This strategy doesn't want wired communication between the distributed renewable sources nor dump masses to dissipate the excess of generated power in the micro grid. These technical benefits create the proposed strategy a promising tool to extend the viability and reliability of the renewable power generation system installed in isolated and remote communities. By the proposed active.

Power control, SoC of the ESS will be kept among the safe limits by automatically adjusting the power generation from the Wind, PV systems and load consumption. This coordination performance was obtained by using only local controllers and does not rely on external communication links. Therefore, the risk evoked by the failure of the communication links may be avoided and thereby the reliability of the system is enhanced. Finally, the proposed control strategy is verified by simulation results.

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